



The MetSpy MP7 is the next model up from the MP6. Sophisticated ultrasonic (sensors have no moving parts) technology provides the most accurate weather measurements. A Photosynthetically Active Radiation sensor (PAR) is included to facilitate ETo calculations. This digital sensor can connect to a range of AquaSpy telemetry solutions, fully complementing soil moisture monitoring and making it the ultimate climate monitoring solution.

Automatic Weather Station

Wind

Wind speed	
Range	0...60 m/s
Response time	0.25 s
Available variables	average, maximum and minimum
Accuracy	± 0.3 m/s or ±2% whichever is greater
Output resolution	0.1 m/s (km/h, mph, knots)
Units available	m/s, km/h, mph, knots
Wind direction	
Azimuth	0...360°
Response time	250 ms
Available variables	Average, maximum and minimum
Accuracy	± 2°
Output resolution	1°
Measurement frame	
Averaging time	1...600 s (= 10 min), at one second steps on the basis of 0.25 second samples
Update interval	1...3 600 s (= 60 min), at one second steps

Liquid Precipitation

Rainfall	
	cumulative accumulation after latest automatic or manual reset
Collecting area	60 cm ²
Output resolution	0.01 mm (0.001 in)
Accuracy	5%*
Units available	mm, in
Rain duration	
	counting each ten second increment whenever droplet detected
Output resolution	10 s
Rain intensity	
	one minute running average in ten second steps
Range	0...200 mm/h (broader range with reduced accuracy)
Output resolution	0.1 mm/h (0.01 in/h)
Units available	mm/h, in/h
Hail	
	cumulative amount of hits against collecting surface
Output resolution	0.1 hits/cm ² (1 hits/in ²)
Units available	hits/cm ² , hits/in ² , hits
Hail duration	
	counting each ten second increment whenever hailstone detected
Output resolution	10 s
Hail intensity	
	one minute running average in ten second steps
Output resolution	0.1 hits/cm ² h (1 hits/in ² h)
Units available	hits/cm ² h, hits/in ² h, hits/h

* Due to the nature of the phenomenon, deviations caused by spatial variations may exist in precipitation readings, especially in short time scale. The accuracy specification does not include possible wind induced error.

WINDCAP[®] Sensor

← Transducer separation length, L →

1 Transmit → Time of flight, t_1 → 2 Receive

→ V_w →

Parallel component of wind velocity

1 Receive ← Time of flight, t_2 ← 2 Transmit

For static speed of sound V_s : $\frac{1}{t_1} = \frac{V_s + V_w}{L}$ and $\frac{1}{t_2} = \frac{V_s - V_w}{L}$

Combine to remove V_s : $V_w = \frac{L}{2} \left(\frac{1}{t_1} - \frac{1}{t_2} \right)$

Solve for V_w

Time-of-flight for a sonic impulse from the transmit transducer to the receive transducer is determined for both directions. Simple algebra allows solving for the parallel component of wind velocity independently of the static speed of sound.

Basis set 1: A, B, C

Basis set 2: B, C, A

Basis set 3: A, C, B

The equilateral triangle configuration of the three transducers provides three possible sets of basis vectors. The combinations yield bi-directional measurements on the paths labeled A, B and C. These measurements are used to determine the wind velocity components parallel to each of the three paths.

RAINCAP[®] Sensor

V_j , V_3 , V_2 , V_1

$U_j \propto V_j$

$\rightarrow P = f(U)$

The precipitation sensor detects the impact of individual raindrops. The voltage signals U_j resulting from the impacts are proportional to the volume of the drops V_j and therefore, the signal of each drop can be directly converted to accumulated precipitation P .

